The video presents recent work on deformable object manipulation carried out at SIGMA Clermont / Institut Pascal. Several works are included on the topics of monocular shape tracking and shape servoing in 3D for isometrically deforming objects, dual arm coordination for shape control of linear objects, multirobot coordination based on deformation, and manipulation of deformable objects based on force sensing and finite element modeling.

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Workshop Website:  
http://commandia.unizar.es/irosworkshop2020/

Conference Website:  
https://www.iros2020.org/