F1/10 Autonomous Racing Research and Education

Madhur Behl

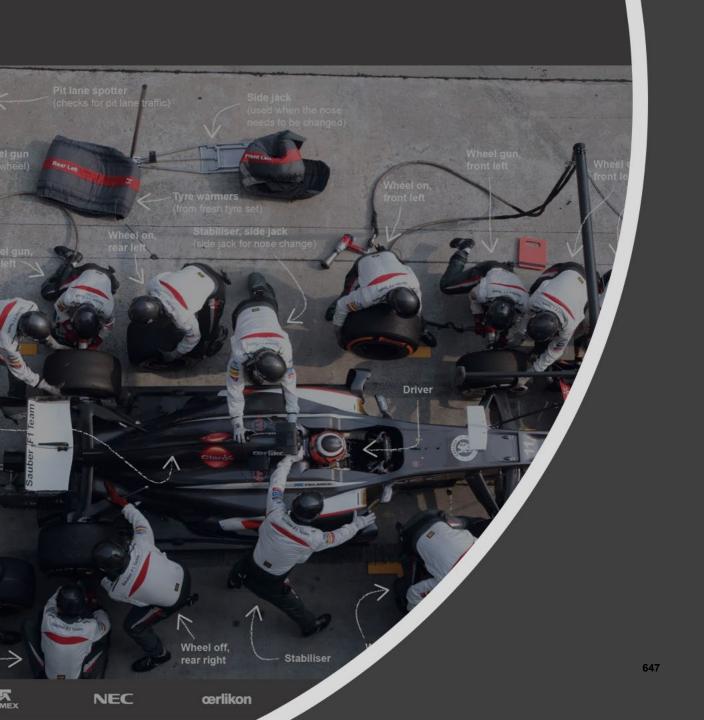
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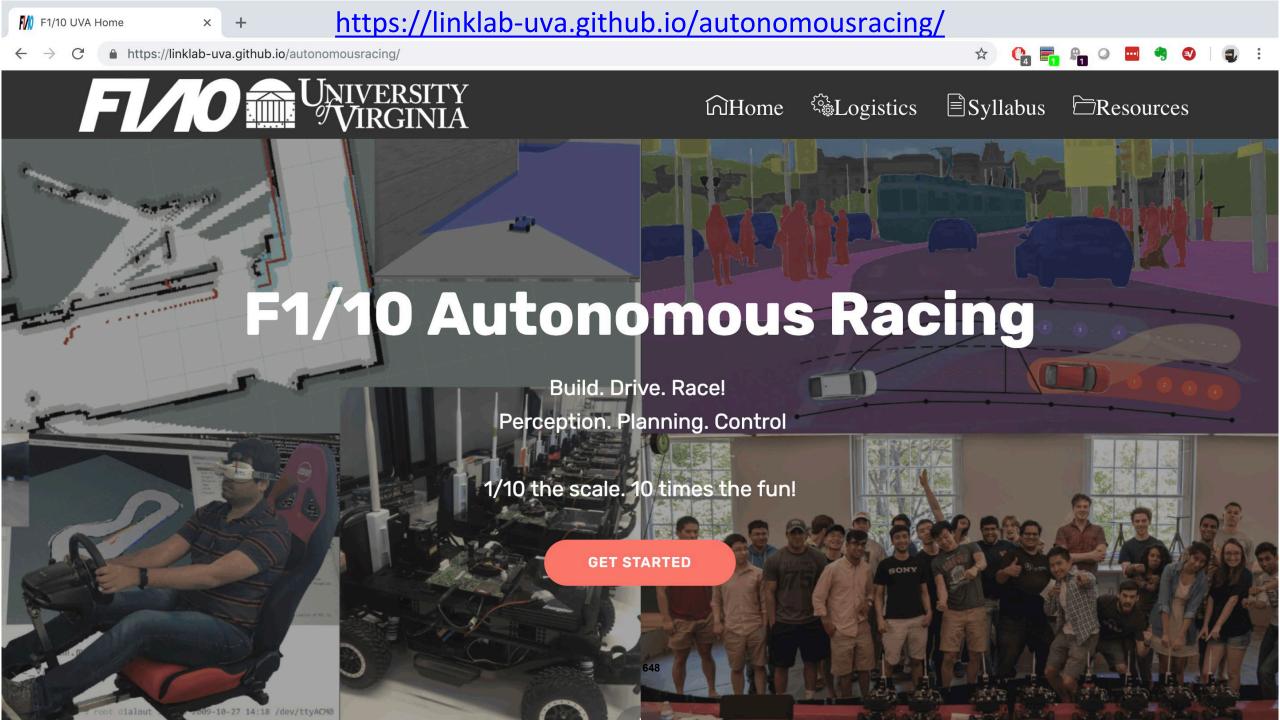








Educating Autonomous Systems Engineers

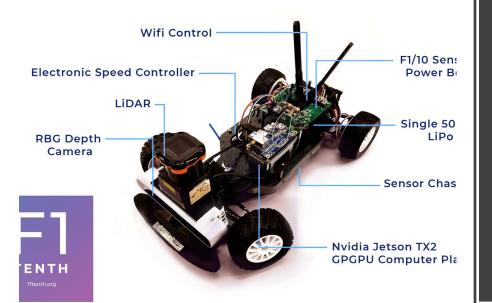




CAVALIER AUTONOMOUS RACING CAVALIER RACING University of Virginia's Autonomous autonomous racing. dev **Team** 650

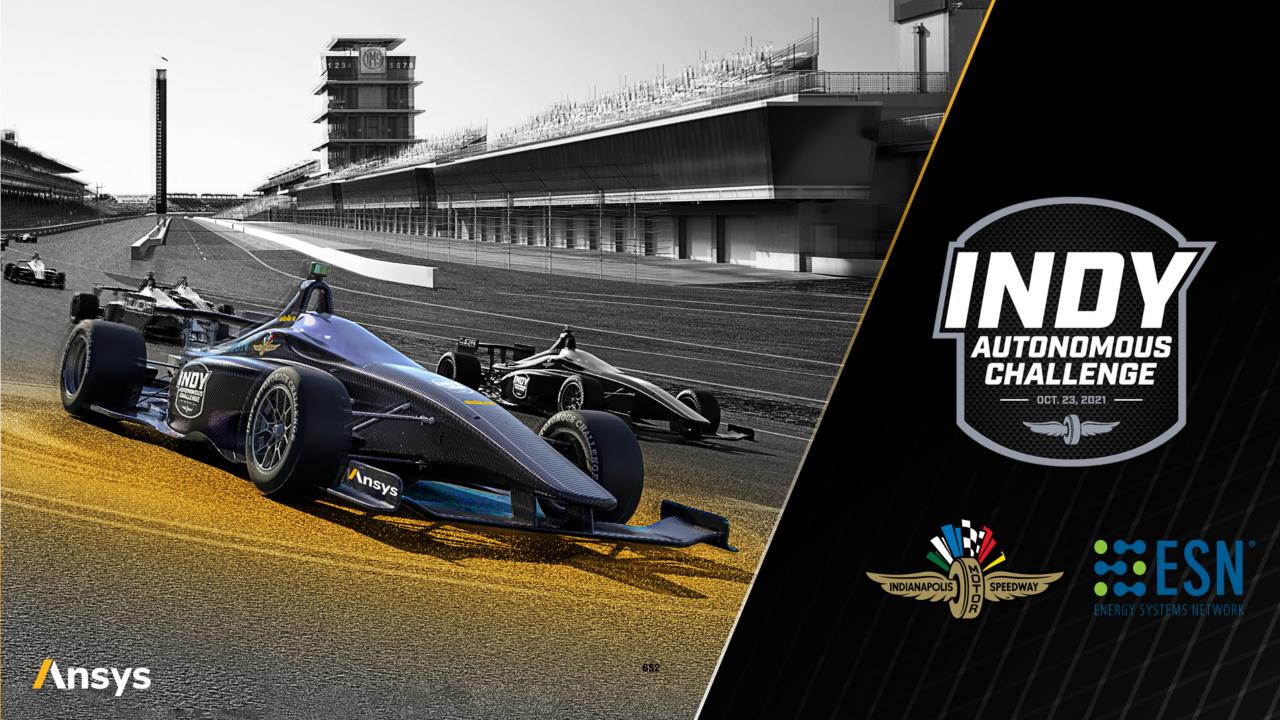






Competitive Autonomous Racing at every scale

651



─ SORT

TAs: Varundev Sureshbabu, Sandesh Banskota,



F1/10 Sim-Tools Package rviz

Move around using mouse

(this area)



[F1/10 Lectures] Introduction to Robot Operating System (ROS) Madhur Behl 1:09:21

1:03:15

[F1/10 Lectures] ROS Filesystem and Catkin Make

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[F1/10 Lectures] ROS Publishing and Subscribing

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[F1/10 Lectures] - Lab Session: Beginner tutorials

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[F1/10 Lectures] ROS Services, Launch and Bags

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[F1/10 Lectures] ROS Transformations and Coordinate Frames

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[F1/10 Lectures] Online ROS F1/10 Simulator

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[F1/10 Lectures] Wall Following Assignment

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[F1/10 Lectures] Simultaneous Localization and Mapping - SLAM

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[F1/10 Lectures] Localization Using Particle Filters

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[F1/10 Lectures] Follow-the-gap

