



IROS 2020 Workshop Application-Driven Soft Robotic Systems: Translational Challenges

Video presentation of:

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Presentation Title
TBC

Presentation Abstract
TBC

Biography

David Noonan earned a B.Eng in Mechatronics Engineering from Dublin City University, an M.Sc in Mechanical Engineering from King's College London, and a Ph.D. from Imperial College London. He worked on Image Guided Robotics and Fiber Optic RealShape (FORS) technology as a Research Scientist at Philips Research North America before joining Auris Health (formerly Auris Surgical Robotics) in 2015. At Auris Health, David is the Director of Systems, Algorithms and Robotics. He helped lead the development of the Monarch Platform, the first robotic system for peripheral nodule bronchoscopy, and is currently working on the next clinical application for the Platform.