

Ergonomic Human-Robot Collaboration: Opportunities and Challenges - The List of Short Presentation

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All authors of selected papers are expected to give a short presentation of their paper for 3-5 minutes.

- 1) Saadullah Khan, Mohd. Yasir Khan, and Osama Naushad, “Ergonomics Evaluation for the Operation Performed on Lathe Machine Using Energy Expenditure Prediction Program”
- 2) Keya Ghonasgi, Saad Yousaf, Paria Esmatloo, Ruth Heckler, Job Ramirez, Chad Rose and Ashish Deshpande, “Design and Validation of a Sensorized Physical Human-Robot Interface for Distributed Force Measurement”
- 3) Marta Lorenzini, Wansoo Kim, Elena De Momi and Arash Ajoudani, “An Online Human Monitoring System for the assessment of multiple ergonomic risk factors”