



# IEEE IROS 2020 Workshop on *Animal-Robot Interaction*

## Title

*FishSim* Animation Toolchain: an innovative tool pushing the boundaries of studies on fish Behavior

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## Abstract

Here I present the results of an interdisciplinary collaboration between biologists and computer scientist at University of Siegen (Germany). Using an innovative approach combining 3D computer animation and a robotic system, we developed the free and open-source *FishSim* Animation Toolchain (short: *FishSim*). *FishSim* combines different tools for the design and animation of virtual fish stimuli, as well as their presentation on screen during behavioral experiments. Even though *FishSim* was specifically tailored for the study of mate-choice copying in sailfin mollies (*Poecilia latipinna*), its framework can be adapted to other fish species and research questions as well. Using examples from our own research, we show how visual information (e.g., morphology and behavior) may be manipulated during experiments and we demonstrate the high degree of control and standardization that can be achieved. Further, *FishSim* enables closed-loop interactions between virtual and live fish. By implementing a 3D tracking system, we show that a virtual male can follow the position of a live focal female on screen and perform courtship behavior according to predefined criteria. Overall, closed-loop computer animation provides a more natural stimulus experience and paves the way for the study of social communication, in which a virtual animal may respond to the behavior expressed by a live counterpart in real-time.